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BLOW-UP OF SMOOTH SOLUTIONS OF THE PROBLEM FOR THE KORTEWEG-DE VRIES-BURGERS EQUATION WITH THE HILFER FRACTIONAL DIFFERENTIAL OPERATOR

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Abstract. This work is devoted to studying the non-existence of the global-in-time solutions for the Korteweg-de Vries-Burgers equation including Hilfer time fractional differential operator which in particular cases of the parameters follows the classical and other time-fractional Korteweg-de Vries-Burgers equation. Applying the method of nonlinear capacity which was suggested by S.I. Pokhozhaev for some initial-boundary value problems, it has been obtained sufficient conditions for the non-existence of global solutions.

Keywords: Hilfer derivative, the method of nonlinear capacity, non-existence of the solution.

РАЗРУШЕНИЕ ГЛАДКИХ РЕШЕНИЙ ЗАДАЧИ ДЛЯ УРАВНЕНИЯ КОРТЕВЕГА-ДЕ ВРИСА-БЮРГЕРСА С ОПЕРАТОРОМ ДРОБНОГО ДИФФЕРЕНЦИАЛА ХИЛЬФЕРА

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Аннотация. Настоящая работа посвящена изучению отсутствия глобальных по времени решений уравнения Кортевега-де Фриза-Бюргерса, включающего дробно-дифференциальный оператор Гильфера по времени, который в частных случаях параметров следует классическому и другим дробным по времени уравнениям Кортевега-Бюргерса. уравнение де Фриза-Бюргерса. Применяя метод нелинейной емкости, предложенный С.И. Похожаевым для некоторых начально-краевых задач, получены достаточные условия отсутствия глобальных решений.

Ключевые слова: производная Гильфера, метод нелинейной емкости, отсутствие решения.

1. PRELIMINARIES. In this section, we give some basic concepts of fractional calculus. **Definition 1.1.** [1] Let $f \in L([a,b])$. The following integrals

$$I_{a+}^{\alpha}[f](t) = \frac{1}{\Gamma(\alpha)} \int_{a}^{t} (t-s)^{\alpha-1} f(s) ds$$
 (1.1)

and

$$I_{b-}^{\alpha}[f](t) = \frac{1}{\Gamma(\alpha)} \int_{t}^{b} (s-t)^{\alpha-1} f(s) ds$$
 (1.2)

are called the left-sided and the right-sided Riemann-Liouville integrals of the fractional order $\alpha > 0$, respectively, where $\Gamma(z)$ denotes the Euler's gamma function.

Definition 1.2. The Riemann-Liouville left-sided fractional derivative $D_{a+}^{\alpha}f$ of order $\alpha(0<\alpha<1)$ is defined by

$$D_{a+}^{\alpha}[f](t) = \frac{d}{dt}I_{a+}^{1-\alpha}[f](t) = \frac{1}{\Gamma(1-\alpha)}\frac{d}{dt}\int_{a}^{t}(t-s)^{-\alpha}f(s)ds.$$
 (1.3)

Definition 1.3. The Riemann-Liouville right-sided fractional derivative $D_{b-}^{\alpha}f$ of order $\alpha(0<\alpha<1)$ is defined by

$$D_{b-}^{\alpha}[f](t) = -\frac{d}{dt}I_{b-}^{1-\alpha}[f](t) = -\frac{1}{\Gamma(1-\alpha)}\frac{d}{dt}\int_{t}^{b}(s-t)^{-\alpha}f(s)ds.$$
 (1.4)

Definition 1.4. The Hilfer derivative $D_{a+}^{\alpha,\beta}f$ of order $0<\alpha<1$ and type $0\leq\beta\leq1$ is defined by

$$D_{a+}^{\alpha,\beta}[f](t) = I_{a+}^{\beta(1-\alpha)} \frac{d}{dt} I_{a+}^{(1-\beta)(1-\alpha)}[f](t)$$
 (1.5)

where I_{a+}^{σ} , $\sigma > 0$ is the Riemann-Liouville fractional integral.

The Hilfer derivative was introduced in [2], [3]. These references provide information about the applications of this derivative and how it arises. It is easy to see that this derivative interpolates the Riemann-Liouville fractional derivative $(\beta = 0)$ and the Caputo fractional derivative $(\beta = 1)$ (see [1]).

The fractional integration by parts is defined as follows.

Lemma 1.1. Le $\alpha > 0$, $p \ge 1$, $q \ge 1$ and $\frac{1}{p} + \frac{1}{q} \le 1 + \alpha$ ($p \ne 1$ and $q \ne 1$ in the

case
$$\frac{1}{p} + \frac{1}{q} = 1 + \alpha$$
). If $\varphi \in L_p(a,b)$ and $\psi \in L_q(a,b)$, then

$$\int_{a}^{b} \varphi(t) I_{a+}^{\alpha} [\psi](t) dt = \int_{a}^{b} \psi(t) I_{b-}^{\alpha} [\varphi] dt.$$
 (1.6)

2. NON-EXISTENCE OF THE SOLUTION OF TIME-FRACTIONAL KORTEWEG-DE-VRIES-BURGERS EQUATION

Let denote by $\Pi_{a,b}$ a rectangular domain of \mathbf{R}^2 , i.e $\Pi_{a,b} = \{(t,x) \in \mathbf{R}^2 : 0 < t < T, a < x < b\}$. In the domain $\Pi_{a,b}$, we consider the time-fractional Korteweg-de Vries-Burgers equation

$$D_{0+,t}^{\alpha,\beta}u(t,x) + u(t,x)u_x(t,x) + u_{xxx}(t,x) = vu_{xx}(t,x)$$
(2.1)

with the following initial condition

$$I_{0+,t}^{\gamma-1}u(0,x) = u_0(x), x \in [a,b], \tag{2.2}$$

where $D_{a+}^{\alpha,\beta}$ is the Hilfer derivative of order $0 < \alpha < 1$ and type $0 \le \beta \le 1$ with respect to t, v > 0 and $u_0(x)$ is a given function.

If $\beta = 1$ then the equation (2.1) takes the form which studied in [4]. And when $\beta = 1$ and $\alpha = 1$ it becomes the classical Korteweg-de Vries-Burgers equation [5]. We should note the

Korteweg-de Vries-Burgers equation can be applied as the mathematical model for many real-life processes [5].

Our aim is to investigate blow-up solutions of the problem (2.1)-(2.2). To do this we apply the method of nonlinear capacity. This concept for analyzing blow-up of solutions nonlinear equations was suggested by Pokhozhaev in [6].

We consider a class $\Phi(\Pi_{a,b})$ of test functions $\varphi(t,x)$, defined on the domain $\Pi_{a,b}$ with arbitrary parameters T>0, $a,b\in \mathbf{R}$, have the following properties:

(i)
$$\varphi_t, \varphi_{xx}, \varphi_{xxx} \in C(\Pi_{a,b});$$

(ii)
$$\varphi_x \ge 0$$
 in $\Pi_{a,b}$;

(iii)
$$I_{T-t}^{\beta(1-\alpha)}\varphi(x,t)=0$$
 at $t=T$ and $x \in (a,b)$;

(iv)
$$\zeta\left(\Pi_{a,b}\right) = \iint_{\Pi_{a,b}} \frac{\left(L^*\varphi\right)^2}{\varphi_x} dt dx < +\infty,$$

where $L^* \varphi = -I_{T-,t}^{(1-\beta)(1-\alpha)} D_{T-,t}^{1-\beta(1-\alpha)} \varphi + \nu \varphi_{xx} - \varphi_{xxx}$.

Suppose that there exists an T>0 for which weak solution of the problem (2.1)-(2.2) satisfying $u_{xx}, D_{0+,t}^{\alpha,\beta}u \in C([a,b]\times[0,t])$.

By multiplying the equation (2.1) by a test function $\varphi \in \Phi(\Pi_{a,b})$ and then integrating over $\Pi_{a,b}$ obtained equality, we get

$$\iint_{\Pi_{a,b}} \varphi(t,x) D_{0+,t}^{\alpha,\beta} u(t,x) dt dx + \iint_{\Pi_{a,b}} \varphi(t,x) u(t,x) u_x(t,x) dt dx +$$

$$+ \iint_{\Pi_{a,b}} \varphi(t,x) u_{xxx}(t,x) dt dx = v \iint_{\Pi_{a,b}} \varphi(t,x) u_{xx}(t,x) dt dx \cdot$$
(2.3)

Applying the rule of integration by parts, it is easy to obtain the following equalities

$$\iint_{\Pi_{a,b}} \varphi(t,x)u(t,x)u_{x}(t,x)dtdx =$$

$$= \frac{1}{2} \int_{0}^{T} u^{2}(t,x)\varphi(t,x)|_{a}^{b}dt - \frac{1}{2} \iint_{\Pi_{a,b}} u^{2}(t,x)\varphi_{x}(t,x)dtdx, \qquad (2.4)$$

$$\iint_{\Pi_{a,b}} \varphi(t,x)u_{xx}(t,x)dtdx =$$

$$= \int_{0}^{T} \left[u_{x}(t,x)\varphi(t,x) - u(t,x)\varphi_{x}(t,x) \right] \Big|_{a}^{b}dt - \iint_{\Pi_{a,b}} u(t,x)\varphi_{xx}(t,x)dtdx, \qquad (2.5)$$

$$\iint_{\Pi_{a,b}} \varphi(t,x) u_{xxx}(t,x) dt dx =$$

$$\int_{0}^{T} \left[\varphi u_{xx} - \varphi_{x} u_{x} + \varphi_{xx} u \right]_{a}^{b} dt - \iint_{\Pi} \varphi_{xxx}(t,x) u(t,x) dt dx \qquad (2.6)$$

Using Definition 1.4 and applying Lemma 1.1, we have

$$\iint_{\Pi_{a,b}} \varphi(t,x) D_{0+,t}^{\alpha,\beta} u(t,x) dt dx = \iint_{\Pi_{a,b}} \varphi(t,x) I_{0+}^{\beta(1-\alpha)} \frac{d}{dt} I_{0+}^{(1-\beta)(1-\alpha)} u(t,x) dt dx =$$

$$= \iint_{\Pi_{-t}} I_{T-,t}^{\beta(1-\alpha)} \varphi(t,x) \frac{d}{dt} I_{0+}^{(1-\beta)(1-\alpha)} u(t,x) dt dx .$$

Hence, applying the rule of integration by parts and using Lemma 2.1, we obtain

$$\begin{split} \iint_{\Pi_{a,b}} \varphi(t,x) D_{0+,t}^{\alpha,\beta} u(t,x) dt dx &= \int_{a}^{b} \left\{ I_{0+,t}^{(1-\beta)(1-\alpha)} u(t,x) I_{T-,t}^{\beta(1-\alpha)} \varphi(t,x) \right\} \bigg|_{0}^{T} dx - \\ &- \iint_{\Pi_{a,b}} \frac{d}{dt} I_{T-,t}^{\beta(1-\alpha)} \varphi(t,x) I_{0+}^{(1-\beta)(1-\alpha)} u(t,x) dt dx = \\ \int_{a}^{b} \left\{ I_{0+,t}^{(1-\beta)(1-\alpha)} u(t,x) I_{T-,t}^{\beta(1-\alpha)} \varphi(t,x) \right\} \bigg|_{0}^{T} dx - \iint_{\Pi_{a,b}} u(t,x) I_{T-,t}^{(1-\beta)(1-\alpha)} \frac{d}{dt} I_{T-,t}^{\beta(1-\alpha)} \varphi(t,x) dt dx \,. \end{split}$$

Taking this and equalizes (2.4), (2.5) into account and also using Definition 2.3, from (2.3) we drive

$$\frac{1}{2} \iint_{\Pi_{a,b}} u^{2}(t,x) \varphi_{x}(t,x) dt dx = -\iint_{\Pi_{a,b}} u(t,x) \left(L^{*}\varphi\right)(t,x) + \\
+ \iint_{a} \left\{ I_{0+,t}^{(1-\beta)(1-\alpha)} u(t,x) I_{T-,t}^{\beta(1-\alpha)} \varphi(t,x) \right\} \left| \int_{0}^{T} dx + \int_{0}^{T} B\left(u(t,x), \varphi(t,x)\right) \right|_{a}^{b} dt ,$$
(2.7)

where

$$B(u(t,x),\varphi(t,x)) = \frac{1}{2}u^{2}(t,x)\varphi(t,x) - vu_{x}(t,x)\varphi(t,x) + vu(t,x)\varphi_{x}(t,x) + \varphi_{x}(t,x)u_{x}(t,x) - \varphi_{x}(t,x)u_{x}(t,x) + \varphi_{x}(t,x)u(t,x).$$

Taking (2.2) and (iii) property of test functions, from the last we get

$$\frac{1}{2} \iint_{\Pi_{a,b}} u^{2}(t,x) \varphi_{x}(t,x) dt dx = -\iint_{\Pi_{a,b}} u(t,x) (L^{*}\varphi)(t,x) dt dx + \int_{0}^{T} B(u(t,x),\varphi(t,x)) \Big|_{a}^{b} dt - -\int_{a}^{b} u_{0}(x) I_{T-,t}^{\beta(1-\alpha)} \varphi(x,t) dx. \tag{2.8}$$

By applying Hölder and Young's inequalities, it is easy to see that

$$\left| \iint_{\Pi_{a,b}} u(t,x) \Big(L^* \varphi \Big)(t,x) dt dx \right| = \left| \iint_{\Pi_{a,b}} u(t,x) \sqrt{\varphi_x(x,t)} \frac{\Big(L^* \varphi \Big)(t,x)}{\sqrt{\varphi_x(x,t)}} dt dx \right| \le$$

$$\left(\iint_{\Pi_{a,b}} u^2(t,x) \varphi_x(t,x) dt dx \right)^{1/2} \left(\iint_{\Pi_{a,b}} \frac{\Big(\Big(L^* \varphi \Big)(t,x) \Big)^2}{\varphi_x(x,t)} dt dx \right)^{1/2} \le$$

$$\frac{1}{2} \iint_{\Pi_{a,b}} u^2(t,x) \varphi_x(t,x) dt dx + \frac{1}{2} \iint_{\Pi_{a,b}} \frac{\Big(\Big(L^* \varphi \Big)(t,x) \Big)^2}{\varphi_x(x,t)} dt dx .$$

Taking this inequality and (iv) property of test functions into account from (2.8), we have

$$0 \le \frac{1}{2} \zeta \left(\Pi_{a,b} \right) + \int_{0}^{T} B\left(u(t,x), \varphi(t,x) \right) \Big|_{a}^{b} dt - \int_{a}^{b} u_{0}(x) I_{T-,t}^{\beta(1-\alpha)} \varphi(x,t) \Big|_{t=0} dx . \quad (2.9)$$

The following theorem is valid:

Theorem 3.1. Suppose that the boundary conditions and the initial function $u_0(x) \in L[a,b]$ satisfy the following assumption: there exists a function $\varphi(x,t) \in \Phi(\Pi_{a,b})$ such

that $B(u(t,x),\varphi(t,x))\Big|_a^b \in L[0,T]$ and the following inequality

$$\frac{1}{2}\zeta(\Pi_{a,b}) + \int_{0}^{T} B(u(t,x),\varphi(t,x)) \Big|_{a}^{b} dt - \int_{a}^{b} u_{0}(x) I_{T-,t}^{\beta(1-\alpha)} \varphi(x,t) \Big|_{t=0} dx < 0.$$
 (2.10)

Then problem (2.1)-(2.2) does not admit a global-in-time solution in $\Pi_{a,b}$ with these initial and boundary conditions.

Proof. Let us assume the opposite i.e. the problem (2.1)-(2.2) admits a global-in-time solution in $\Pi_{a,b}$. Then we arrived at contradiction by virtue of inequalities (2.9) and (2.10).

Now, we consider the fractional Korteweg-de Vries-Burgers equation (2.1) with $\nu = 1$ in the rectangular domain $\Pi_{a,b} = \{(t,x) \in \mathbf{R}^2 : 0 < t < T, 0 < x < 1\}$ with the initial condition (2.2) and the following boundary conditions

$$u(t,0) = \tau_1(t), u_x(t,0) = \tau_2(t), 0 < t < T,$$
 (2.11)

where τ_1 and τ_2 are given functions such that $\tau_1, \tau_2 \in L[0,T]$.

Multiply the time-fractional Korteweg-de Vries-Burgers equation (2.1) by a test function $\varphi \in \mathcal{D}(\Pi_{a,b})$, after some calculations and simplifications we obtain

$$0 < \frac{1}{2} \zeta \left(\Pi_{0,1} \right) + \int_{0}^{T} B \left(u(t,x), \varphi(t,x) \right) \Big|_{0}^{1} dt - \int_{0}^{1} u_{0}(x) I_{T-,t}^{\beta(1-\alpha)} \varphi(x,t) \Big|_{t=0} dx.$$

We take a test function satisfying the following boundary conditions:

$$\varphi(t,1) = 0$$
, $\varphi_x(t,1) = 0$, $0 < t < T$. (2.12)

Then.

$$B(u,\varphi)\Big|_{0}^{1} = -\left[\frac{1}{2}\tau_{1}^{2}(t) - \tau_{2}(t)\right]\varphi(t,0) - \tau_{1}(t)\varphi_{x}(t,0).$$

In this case, the following theorem is valid:

Theorem 2.2. Let the initial-boundary problem (2.1), (2.2), (2.11) be such that there exists a test function $\varphi \in \Phi(\Pi_{0,1})$ satisfying the boundary conditions (2.12) and also the following inequality

$$\frac{1}{2}\zeta(\Pi_{0,1}) < \int_{0}^{T} \left[\frac{1}{2}\tau_{1}^{2}(t)\varphi(t,0) - \tau_{2}(t)\varphi(t,0) + \tau_{1}(t)\varphi_{x}(t,0) \right] dt +
+ \int_{0}^{1} u_{0}(x)I_{T-t}^{\beta(1-\alpha)}\varphi(x,t)|_{t=0} dx.$$
(2.13)

Then the problem (2.1), (2.2), (2.11) does not admit a global-in-time solution in $\Pi_{0.1}$.

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